# Comparing Multi-agent System and Mixed-Integer Programming Approaches on a Simple Optimization Problem

P. Laroque F. Pirard F. Archambault M. Quoy P. Gaussier

ETIS, CNRS UMR8051 / ENSEA / Université de Cergy-Pontoise F95000 France

#### ICAI '10 - 07/15/2010





P. Laroque et al. (ETIS, CNRS UMR805

comparing MAS / MIP

ICAI '10 1 / 12

#### The Problem

- Numerous problems fall into the "search of an extremum" (minimum or maximum) of a given cost – or objective / profit – function problem
- Several approaches, including MIP, can solve the problem in the linear case
  - hard to predict computation time given the input parameters
  - sometimes a "good" solution is enough if one can get it from a faster algorithm
  - unsufficient robustness when faced with great variations in the model dynamics
- MAS approach, based on self-organization principles, may be an answer to such limitations
  - however solution is not optimal. Is it "good"?



イロト イ理ト イヨト イヨト

#### The Problem

- Numerous problems fall into the "search of an extremum" (minimum or maximum) of a given cost – or objective / profit – function problem
- Several approaches, including MIP, can solve the problem in the linear case
  - hard to predict computation time given the input parameters
  - sometimes a "good" solution is enough if one can get it from a faster algorithm
  - unsufficient robustness when faced with great variations in the model dynamics
- MAS approach, based on self-organization principles, may be an answer to such limitations
  - however solution is not optimal. Is it "good"?

- Warehouse location problem: distribute a set of products to a set of client areas from production plants and / or warehouses
- production plant capacity is sufficient to satisfy the customers' requests; warehouse capacity is limited
- We want to know:
  - which warehouse is used and where it is located
  - the product flows (plant/warehouse, plant/customer, warehouse/customer)



- Objective function: sum of delivery and warehouse costs (to minimize)
- Decision variables:
  - existence of a warehouse at a given location (binary)
  - flows (plant warehouse, plant customer, warehouse customer)
- Constraints:
  - satisfy customer area requests
  - respect warehouse capacity
  - respect conservation of flows
- Solving algorithm: Branch-and-bound



ICAI '10

4 / 12



- o motivation-driven agents
- vision "sensor", landmarks & place cells
- "comfort" threshold ; falling below minimum comfort value triggers planning strategy
- "cognitive" agents embed a cognitive map to retrieve complex paths leading to resources
- hebbian learning rules on cognitive map weights allow for learning new paths and forgetting obsolete ones

(日) (周) (日) (日)



#### • motivation-driven agents

- vision "sensor", landmarks & place cells
- "comfort" threshold ; falling below minimum comfort value triggers planning strategy
- "cognitive" agents embed a cognitive map to retrieve complex paths leading to resources
- hebbian learning rules on cognitive map weights allow for learning new paths and forgetting obsolete ones

(日) (周) (日) (日)



- motivation-driven agents
- vision "sensor", landmarks & place cells
- "comfort" threshold ; falling below minimum comfort value triggers planning strategy
- "cognitive" agents embed a cognitive map to retrieve complex paths leading to resources
- hebbian learning rules on cognitive map weights allow for learning new paths and forgetting obsolete ones

(日) (周) (日) (日)



- motivation-driven agents
- vision "sensor", landmarks & place cells
- "comfort" threshold ; falling below minimum comfort value triggers planning strategy
- "cognitive" agents embed a cognitive map to retrieve complex paths leading to resources
- hebbian learning rules on cognitive map weights allow for learning new paths and forgetting obsolete ones

. . . . . . .

# Agent Navigation





< 行い



P. Laroque et al. (ETIS, CNRS<u>UMR805</u>

comparing MAS / MIP

< ≧ > ≧ ICAI '106

6 / 12

- Agents can transport small quantities of goods, and store them when / where they want
- Transport and deposit decisions are probabilistic, based on observations of certain social insects behavior: P(n) (prob. for deposit when n units of resources) is

$$P(n) = 1 - (1-p)^n$$

P. Laroque et al. (ETIS, CNRS UMR805

ICA| '10

7 / 12

#### Experiments

- Fixed resources (plants)
- Environment = 20x20 square grid, cell = (empty, plant, warehouse, customer)
- 10 to 20 agents ("trucks") per test run
- results averaged over ten successive runs (due to randomness in agents behavior)



#### Computing the Results

**0** minimum distance from  $W_i$  to a MAS "correspondent"  $W'_i$ :

$$d_i = \min_j \left( d\left( W_i, W_j' \right) \right)$$

2 average distance for a given experiment  $Exp_k$ :

$$d(Exp_k) = \left(\sum_{i=1}^n \frac{d_i}{n}\right) + p\left(\left|n' - n\right|\right)$$

**\bigcirc** average results on  $N_e$  experiments:

$$d(MAS, MIP) = \frac{1}{N_e} \sum_{i=1}^{N_e} d(Exp_i)$$

P. Laroque et al. (ETIS, CNRS UMR805

ICAI '10 9 / 12

(4) (5) (4) (5)

#### First Results

• The MAS solution (left) is compared to both the MIP solution (best possible, right) and a randomly generated solution (middle):



	MAS solution	random solution
average distance	19.6831	49.4644
standard deviation	8.24	15.73



10 / 12

ICAI '10

P. Laroque et al. (ETIS, CNRS UMR805

comparing MAS / MIP

#### First Results

• The MAS solution (left) is compared to both the MIP solution (best possible, right) and a randomly generated solution (middle):



	MAS solution	random solution
average distance	19.6831	49.4644
standard deviation	8.24	15.73



10 / 12

P. Laroque et al. (ETIS, CNRS UMR805

comparing MAS / MIP

ICAI '10

Next important issues:

- O complexity of the MAS approach when the environment size changes?
- What happens to the MIP and MAS algorithms when things change with time?
  - MAS: cognitive map helps for agents adaptation
  - MIP: modeling technique under construction



11 / 12

ICAI '10

P. Laroque et al. (ETIS, CNRS UMR805

- Accuracy of a MAS approach to simple optimization problems
- MAS solution obtained after a short and predictible delay; "quality" not always predictible
- MIP approach gives best possible results, time needed not always predictible



12 / 12

ICAI '10

P. Laroque et al. (ETIS, CNRS UMR805